

# MCMC CONVERGENCE STUDIES FOR FLOW PROBLEMS WITH MULTISCALE SAMPLING

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# Motivation

Subsurface characterization: What lies in an underground volume?

**Need for the subsurface characterization:** To make decisions regarding economic, environmental, or health and safety concerns.

- ▶ **Oil Recovery**  
Forecasting the output of oil production.
- ▶ **Environmental Contamination**  
Dynamics of contaminant concentration in groundwater.
- ▶ **Geological sequestration of CO<sub>2</sub>**  
Prediction of movement of CO<sub>2</sub> plumes in the underground.

# Challenges in Subsurface Characterization

A reliable characterization of subsurface is one of the most **challenging** tasks.

The challenges arise in several aspects:

- ▶ Nonlinear system of PDEs
- ▶ Hyperbolic dominated problem
- ▶ Very large computational problem
- ▶ Stochastic coefficients/uncertainty
- ▶ Uncertainty reduction: conditioning of reservoir properties to dynamic and/or static data

# A Simplified Description of the Problem

**Goal:** Characterize the permeability field using available pressure data.

**Approach:** Use a new **multiscale sampling algorithm** in a Bayesian framework with an analysis of the convergence of multiple MCMCs.

# Model Problem: Elliptic Equation

Using Darcy's law, we write the elliptic problem as follows:

$$\begin{aligned} \mathbf{v}(\mathbf{x}) &= -k(\mathbf{x}, \omega) \nabla p(\mathbf{x}), \\ \nabla \cdot \mathbf{v}(\mathbf{x}) &= f, \quad \mathbf{x} \in \Omega, \end{aligned}$$

and appropriate Boundary Conditions,

where,

$f$ : source term

$k(\mathbf{x}, \omega)$ : unknown permeability of the porous medium

$\mathbf{v}(\mathbf{x})$ : Darcy velocity

$p(\mathbf{x})$ : pressure of the fluid.

**Numerical Simulator:** Uses a mixed finite element formulation on Graphics Processing Units (GPUs).

# Subsurface Characterization

# Bayes' Theorem

We sample the permeability field,  $\log k(x) = \eta$ , **conditioned** on available pressure data,  $R_p$ , i.e., from  $P(\eta|R_p)$ .

**Bayes' Theorem:**  $P(\eta|R_p) \propto P(R_p|\eta) P(\eta)$

- ▶  $P(R_p|\eta)$  is the likelihood function. We assume the form

$$P(R_p|\boldsymbol{\eta}) \propto \exp\left(-(\mathbf{R}_p - \mathbf{R}_{\boldsymbol{\eta}})^\top \Sigma (\mathbf{R}_p - \mathbf{R}_{\boldsymbol{\eta}})\right),$$

where  $\mathbf{R}_{\boldsymbol{\eta}}$  denotes the simulated pressure data, and  $\Sigma = \mathbf{I}/2\sigma_R^2$ . It deals with the statistical distribution involving the solution of the **elliptic equation**.

- ▶  $P(\eta)$  is the prior distribution (has to be provided).

Many samples of the permeability field may yield the same/similar pressure data (**not one-to-one mapping**). Therefore, this is an ill-posed **inverse problem**.

# The Prior Distribution

Consider a Gaussian field  $Y(x, \omega)$ .

It is characterized by  $R(x, z) = \langle Y(x, \omega)Y(z, \omega) \rangle \quad \langle Y(x, \omega) \rangle = 0$ .

**Example:**  $R(x, z) = \sigma_Y^2 \exp \left( - \sum_{i=1}^2 \frac{(x_i - z_i)^2}{2L_i^2} \right)$

We set, as a simple model for rock permeability,

$$k(x, \omega) = \exp(Y(x, \omega)).$$



# Difficulty in Characterization

Typical permeability field is defined over the underlying grid where the number of grid blocks can be large.

Direct sampling of the permeability field over these grid blocks yields a very large dimensional parameter space.

The Karhunen-Loève Expansion is used to efficiently parametrize the permeability field, resulting in greatly reduced parameter space dimension [Loève, 1977].

# Karhunen-Loève Expansion

It relies on decomposing  $Y$  using basis functions satisfying

$$\int_{\Omega} R(x, z) \varphi_n(z) dz = \lambda_n \varphi_n(x).$$

The Karhunen-Loève Expansion is

$$Y(x, \omega) = \sum_{n=1}^{\infty} \theta_n(\omega) \sqrt{\lambda_n} \varphi_n(x).$$

The **parameter reduction** is achieved by truncating the series:

$$Y(x, \omega) \approx \sum_{n=1}^N \theta_n(\omega) \sqrt{\lambda_n} \varphi_n(x)$$

# Karhunen-Loève Expansion

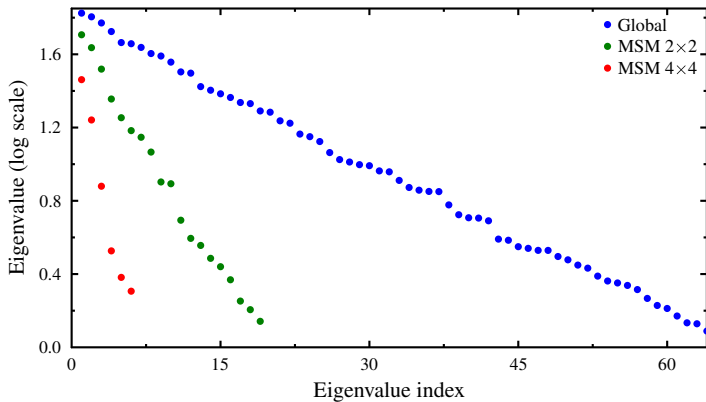


Fig. 1. Decay of eigenvalues for the global and multiscale sampling methods.

# Markov Chain Monte Carlo Methods

# Metropolis-Hasting Markov Chain Monte Carlo

**Goal:** To sample from the posterior dist.  $P(\boldsymbol{\eta}|R_p)$ ,  $\boldsymbol{\eta} = \text{KLE}[\boldsymbol{\theta}]$

**Strategy:** Construct a **Markov chain** such that  $P(\boldsymbol{\eta}|R_p)$  is the equilibrium distribution of the chain.

**Drawbacks:**

It is inherently a **serial** process with **low** acceptance rates.

**Proposed Alternatives:**

- ▶ Preconditioned (Two-stage) MCMC, which uses a coarse scale filter [Christen and Fox, 2005; Efendiev et al., 2005].
- ▶ Parallelize a single MCMC chain by Prefetching [Brockwell, 2006].
- ▶ Multiple MCMC chains.

# Multiscale Sampling

- ▶ Our method combines the simplicity of the **preconditioned MCMC** with a **new multiscale sampling algorithm**.
- ▶ The algorithm decomposes the stochastic space in orthogonal complement subspaces, through a **one-to-one mapping** to a non-overlapping domain decomposition of the region of interest.
- ▶ The localization of the search is performed by **Gibbs sampling**: we apply a **KL expansion locally**, at the subdomain level.

# The Mapping: Prior Distribution and Subdomains

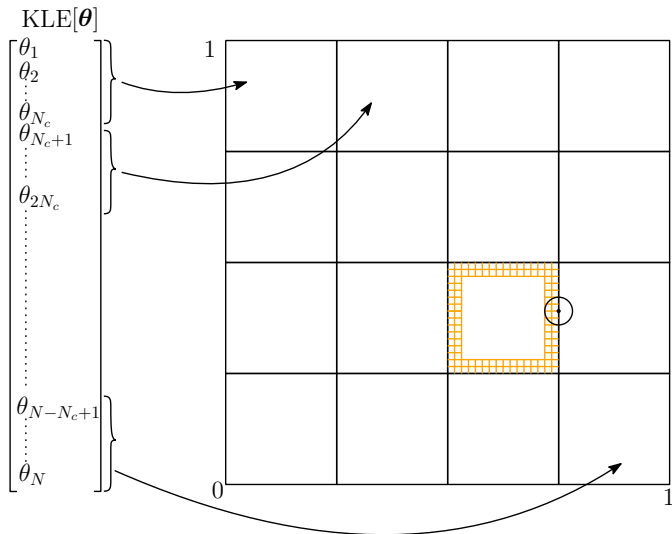


Fig. 2. Decomposition of the theta vector (left) and the domain (right).

# Convergence Analysis of Multiple MCMC Chains

- ▶ Start **multiple** MCMC chains from different initial conditions and make sure that the chains mix together sufficiently.
- ▶ Two most commonly used convergence measures: Potential Scale Reduction Factor (**PSRF**) and its multivariate extension (**MPSRF**).
- ▶ The PSRF takes into account only a subset of parameters; The MPSRF incorporates the convergence information of all the parameters and their interactions [Brooks and Gelman, 1998].



# Simulation Study

## Problem Setup

- ▶ Consider a unit square-shaped physical domain; Solve the elliptic equation in the domain.
- ▶ **Source Term:** Set  $f = 0$ .
- ▶ **Boundary Conditions:** Impose Dirichlet boundary conditions,  $p = 1$  and  $p = 0$ , on the left and right boundaries, respectively; Set no-flow boundary condition everywhere else on the boundaries of the domain.
- ▶ **Subsurface Characterization:** Use MCMC simulations to characterize the permeability field using available pressure data.
- ▶ **Multiscale Sampling Methods:** MSM  $2 \times 2$  ( $H = 0.5$ ) and MSM  $4 \times 4$  ( $H = 0.25$ )

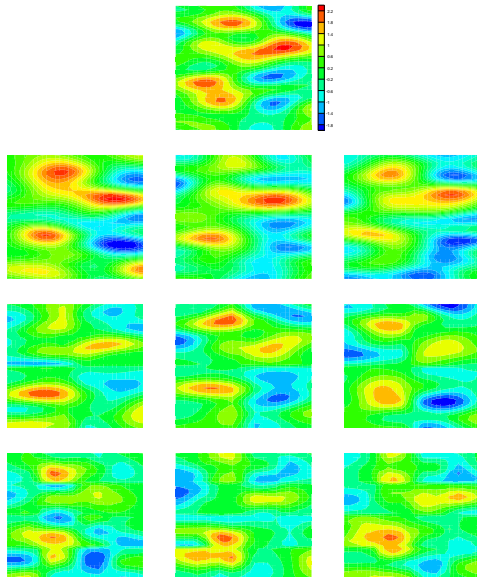


Fig. 3. First row: Reference log permeability field. Second row: Accepted permeability fields in the global sampling method. Third row: Accepted permeability fields in MSM  $2 \times 2$ . Fourth row: Accepted permeability fields in MSM  $4 \times 4$ . From left to right, log permeability fields at 20000, 50000 and 100000 iterations, respectively.

# PSRF and MPSRF Curves

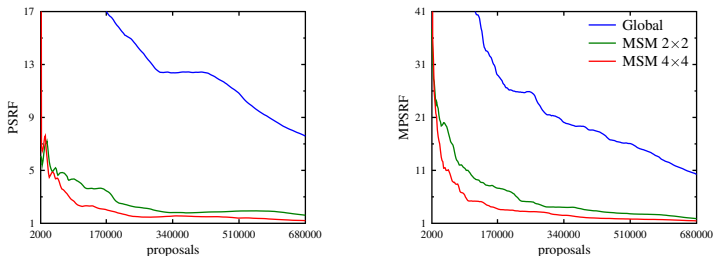


Fig. 4. The maximum of PSRFs and MPSRF for the MCMC method with and without multiscale sampling.

**Much faster** convergence obtained by the MCMC with multiscale sampling.

# Conclusions

- ▶ We presented a novel multiscale sampling method to localize the search in the stochastic space of a Bayesian statistical framework for the subsurface characterization.
- ▶ We used multi-chain studies in a multi-GPU cluster to show that the **new multiscale sampling algorithm** clearly improves the convergence rate of the preconditioned (two-stage) MCMC method.